# Arduino shield kit

## 1. Introduction

The QRP Labs Arduino shield kit is a versatile shield that can be used for various purposes. Write your own Arduino sketch to define the functionality! For example:

- 1) Arduino-controlled QRSS/WSPR Transmitter (like the U3S)
- 2) Si5351A signal generator (VFO, sweeper, etc.)
- 3) GPS-disciplined frequency reference

This shield kit is compatible with the following QRP Labs products, which may be connected/plugged-in to the shield depending on the required functionality:

- 1) Low Pass Filter (LPF) kit (available for LF/MF/HF/VHF bands 2,200m to 6m)
- 2) Relay-switched LPF kit, to expand to six-band filter capability
- 3) Si5351A synthesiser module kit
- 4) OCXO/Si5351A synthesiser module kit
- 5) QLG1 GPS receiver module kit
- 6) Earlier-supplied AD9850 DDS module (available on eBay etc.)

The shield kit is supplied with one BNC connector for RF output; or alternatively the PCB makes provision for up to three SMA connectors (not supplied) for the Si5351A Clk0, Clk1 and Clk2 outputs.





Arduino shield circuit diagram (schematic)

## 2. Parts List

## 2.1 Resistors

- R1 4.7K preset potentiometer, for power amplifier bias adjustment
- R2 4.7K resistor

### 2.2 Capacitors

- C9, 11, 12 100nF (ceramic, marking 104)
- C10 22uF electrolytic capacitor
- C1-4 Capacitors (supplied in the Low Pass Filter kit, if fitted see later text description)

## 2.3 Semiconductors

- D1 1N4148 diode (supplied in the relay-switched LPF board, if fitted)
- Q1 BS170 transistor
- Q2, 3 BS170 transistor (not supplied optional, for higher power output)

## 2.4 Miscellaneous

Push button, S1 Printed circuit board 2x 4-way female header socket 2x 10-way female header socket 2x 8-way Arduino header socket (with long pins) 3x 6-way Arduino header socket (with long pins) 4x nylon M3 nuts 50cm enamelled wire BNC connector FT37-43 toroidal core

## 3. Construction

## 3.1 General construction tips

Parts placement is defined by the silkscreen printed legend on the PCB, so please observe it carefully, paying particular attention to the correct orientation of the semiconductors.

It is best to read this whole manual before you start! This is because there are many ways to build and use this kit. You need to understand which options to install, for your desired use case.



This photo shows various QRP Labs kits that can be used with the shield kit. Top row (left to right): Low Pass Filter (LPF) kit, OCXO/Si5351A synth kit, Si5351A Synth kit, AD9850 DDS module. Bottom row: Arduino Uno, and this QRP Labs Arduino shield kit.

#### **3.2 Construction steps**

Please refer to the parts placement diagram below.



The order of construction is not important. However, a good principle to follow is to install the smaller components first, so that the larger ones do not prevent easy access.

The construction is going to depend largely on your intended use for the shield. The following stages discuss some options you may wish to fit. Please read them all carefully and understand the options!

Also consider, whether you wish to plug any additional shields on top of this shield kit. If you do, then you cannot fit the Si5351A Synthesiser kit (for example) on 10-pin headers; or the Low Pass Filter kit. These modules cannot be plugged in, because that would make this Arduino shield kit too HIGH, and another shield could not be plugged in on top. In this case, it is possible to solder the Si5351A module directly into the shield, without using the supplied 10-pin headers. It is also possible to build the Low Pass Filter directly on the shield PCB, rather than plugging in low pass filter kits using the dual 4-way header system. Of

course, if you solder in the components directly on the shield, then you lose the flexibility of being able to change them (e.g. change the LPF to a different band) just be plugging in a new LPF.

## 3.3 Arduino headers

The fitting of the Arduino headers is mandatory! They are the way the shield will connect to your Arduino board.

Note that there are TWO options here! The Arduino design changed slightly over the years. The older Arduino boards had fewer pins in their headers. The newer versions of Arduino have two extra pins. So please consider both these options carefully and decide which way to fit the headers.

## Option 1 (old style Arduino):

In this case there are two 8-way headers along the top of the board, and two 6-way headers along the bottom of the board. This is the EASIEST option to fit, because the exact headers are supplied in the kit. You can use this option too on a newer Arduino that DOES have the additional pins, because they are in any case NOT used on this shield. However, if you want to plug in other shields above this one, and those shields required the additional connections, then you need to fit the wider connectors.

Please see the following diagram. The headers are fitted in the areas enclosed by the red rectangles. The additional two pins for newer Arduinos are circled in GREEN. They are not connected to anything in this shield.



Be careful to insert the headers in the correct row of holes! Notice that there are two rows of holes along the top, and two along the bottom of the board. The headers fit in the outermost row of holes; however the SAFEST way to ensure you fit the headers in the correct row of holes is to CHECK with your own Arduino!

### Option 2 (new style Arduino):

In this case, you need to fit a 10-pin header at the top left, 8-pin at the top right, 8-pin at the bottom left, and 6-pin at the bottom right.

You will notice that the kit contents do NOT include a 10-pin header. Three 8-pin headers and two 6-pin headers are supplied in the kit. You can fit 8-pin and 6-pin headers at the top right, bottom left and bottom right positions. For the 10-pin header, you are going to have to create your own. To do this, use an 8-pin header, next to a 2-pin header; make the 2-pin header by cutting off 2-connections from the end of the surplus 6-pin header. It is quite easy to do, cut the 2-pin section off using a wire-cutter.

Be careful to insert the headers in the correct row of holes! Notice that there are two rows of holes along the top, and two along the bottom of the board. The headers fit in the outermost row of holes; however the SAFEST way to ensure you fit the headers in the correct row of holes is to CHECK with your own Arduino!

This diagram illustrates the placements of the headers. You should take care to check the alignment of the headers, to make sure that they fit the Arduino. I solder just one pin at the end of each header strip then check, before soldering the others!



This photograph shows the PCB with the four Arduino headers installed; this is Option 1 (above), to suit my Arduino Uno which is an original Rev 1 Uno.



### 3.4 Reset button

A reset button is included with the kit, for those situations where you need to be able to manually cause the Arduino board to reset. You may have a reset button on another shield or the Arduino board. If you wish to fit it on your Arduino shield, then solder it in the position indicated in Red in the diagram below.



#### 3.5 AD9850 DDS module or Si5351A synthesiser module

Probably you are going to want to fit either:

- 1) AD9850 DDS module (available eBay etc)
- 2) QRP Labs Si5351A Synthesiser module kit
- 3) QRP Labs OCXO/Si5351A Synthesiser module kit

For this you may wish to install the two 10-way female header sockets supplied, in the positions indicated in red in the following diagram:



Notice (see photo, above right) that when the Si5351A synthesiser kit is plugged in, the height above the Arduino PCB will mean that you cannot plug in additional Arduino shields in a stack above the QRP Labs Arduino shield.

Therefore another option, for people who need to be able to plug in another shield on top of this one, is NOT to use the 10way headers at all. Instead, the AD9850 DDS module, or Si5351A module kit, can be soldered directly into the shield PCB. Not using the 10-way headers will make the overall height of the shield low enough, to be able to plug in another Arduino shield on top. This is shown in this photo.

In this case, you would lose the ability to fit the optional RL1 and D1 components (for LPF band switching), because these normally fit UNDER the synthesiser module. Furthermore you would not be able to fit components in the prototyping area under the synthesiser module, on the right side of the board.

You can also construct a Low Pass Filter directly on the shield PCB, rather than plugging it in using the 4way headers.

## 3.6 Power Amplifier (PA)

If you wish to use the Power Amplifier (PA) circuit, then you need to install the following components as indicated in red in the diagram below:





R1: 4.7K trimmer potentiometer (resistor), this sets the PA bias voltage

R2: 4.7K fixed resistor (colour bands yellow-purple-red-gold)

C9, C11 and C12: these are 100nF ceramic capacitors (code "104" written on the capacitor body)

C10: 22uF electrolytic capacitor: take care to fit the capacitor with the correct polarity!

Q1: BS170 transistor; take care to align the transistor body with the flat side along the board edge!

L4: 25 turns on FT37-43 toroid (black colour). Take care to ensure proper solder connection, by scraping away or burning away the enamel insulation. I find holding the iron on the joint for 10 seconds works well.

The following diagram illustrates the correct connection pads for the ends of the inductor L4.



Note that the PCB has space for THREE of the BS170 transistors. You can fit the additional transistors Q2 and Q3 (not supplied, but available from QRP Labs), if you want to increase the power output of the amplifier. Merely adding the extra parallel transistors typically does NOT increase the output power; you also need to increase the PA voltage. The advantage of the three transistors in parallel is that they share the HEAT dissipation; this way you can dissipate more heat, without destroying the BS170 transistors.

The maximum allowable power dissipation of the BS170 transistors is 830mW per transistor. This is power DISSIPATION which is not the same as POWER OUTPUT. Power output is efficiency multiplied by total power consumption. Power dissipation is total power consumption minus power output.

For example, suppose you connect a 9V supply, and you measure a current of 100mA drawn through the 9V supply by the PA circuit. This is a power consumption of 900mW (because Power = Voltage \* Current). Now suppose you measure an RF output power of 600mW on your power meter (or oscilloscope, spectrum analyser, etc.). Then the efficiency of the PA is 67% (RF output power 600mW divided by input DC supply power 900mW). The power dissipation in the PA transistors is 300mW.

You will also need to decide how to power the PA, and fit an appropriate wire jumper accordingly. There are 4 pads by the Arduino Digital I/O connector strip near the centre-top of the PCB. These are labelled VExt, PA, 5V, Vin. You must connect a jumper wire between "PA" and one of the other three pads (VExt, 5V, Vin).

- **VExt**: The PA voltage is supplied by an externally supplied voltage, which is connected at two pads as shown in the diagram below (PA+ and Ground).
- **5V**: The PA voltage is supplied from the Arduino's 5V supply rail



Vin: The PA voltage is supplied from the Arduino's unregulated DC input voltage (IF used).

In the example in the diagram, the jumper is selected to use the external PA voltage option, supplied by connections to the pads PA+, Ground.

## 3.7 Low Pass Filter

Following the Power Amplifier, you may wish to install a Low Pass Filter module kit. To do this, you should fit the 4-way female header sockets as indicated in red in this diagram. Snip off a few mm of the 4-way "IN" header connector pins on the underside of the board, to avoid short circuit against the top of the Arduino USB connector! Check and you will see what I mean.

In order to route the RF signal through the LPF and to the RF Output connector (BNC) on the shield, you will also need to fit wire jumpers between W0/W1 and W2/W3. These jumpers bypass the relay RL1. You can use proper pin-header jumpers if you wish; or you can solder in wire offcuts left over from other components. When soldering in a wire jumper, I always fit the wire jumper as a small loop, about 5mm high, rather than a straight wire flat on the board. This makes it very easy to cut the wire later, if I decide I don't want that jumper. Cutting the wire is easier than removing by de-soldering!

If you are going to install the Relay-Switched Filter kit, this comes with 6 relays and 6 1N4148 diodes. Five of the relays/diodes are installed on the relay PCB, and the 6<sup>th</sup> set are installed in positions RL1 and D1 on the Arduino shield. In this case, you will NOT need to fit the W0/W1 and W2/W3 jumpers.



Another option, is to solder the LPF components directly to the shield PCB, rather than the LPF PCB. This option would suit people who need to plug in another Arduino shield on top of this one, so they cannot tolerate the height of the LPF kit plugged in using 4-way headers. Notice that the LPF components L1, L2, L3 and C1, C2, C3, C4 are placed identically to the equivalent components in the LPF kit. You can follow the same instructions as the LPF kit, except install the components on the Arduino shield, not the LPF kit. In this case, you will want to install the LPF kit components as highlighted in red, below. The yellow rectangles are space for additional parallel capacitors for C1, C2, C3 and C4 respectively, if they are needed in order to achieve the required capacitance. Please see LPF kit documentation for details.



Here's a photo of the board so far, including PA, LPF sockets, Synth sockets, and Reset button.



## 3.8 RF Output options

The diagram (right) shows an example output arrangement. It shows the main RF output using the supplied BNC connector (coloured red); furthermore the Si5351A's Clk1 and Clk2 outputs are available at two pads labelled RF1 and RF2 respectively. If an AD9850 DDS module is used, not an Si5351A Synthesiser module, then these two outputs would be the AD9850 DDS' two sinewave outputs.

The RF Output (labelled Clk0) is the Si5351A (or AD9850 DDS squarewave) output after amplification in the PA and filtering in the LPF (if fitted).



Another way to arrange output connectors is to use edge-mounted SMA connectors. The PCB layout is designed to accommodate three edge-mounted SMA connectors, illustrated in red in the following diagram. This type of connector has four grounded mounting arms, which are designed to fit over the edge of a standard 1.6mm thick PCB, two above, two below. Then solder the grounded mounting arms, and solder the centre connector (above board).

Again, Clk1 and Clk2 will be the sinewave outputs if the AD9850 DDS module is used. The RF Output (labelled Clk0) is the Si5351A (or AD9850 DDS squarewave) output after amplification in the PA and filtering in the LPF (if fitted).



It's important to note that the Clk1 and Clk2 outputs are connected directly to the Si5351A module (these will be the sinewave outputs, if the AD9850 DDS module is used). On the other hand, the Clk0 output is NOT directly connected to the Si5351A Clk0 output (which would be one of the squarewave outputs if the AD9850 DDS is used).

If you wish to use the Si5351A Clk0 output directly (or AD9850 DDS squarewave comparator output), not fitting any PA or LPF components, then you will need to arrange to route the signal from pin 17 of the Si5351A module to the output BNC connector. An example is shown below. You can trace the track from pin 17 (shown in yellow), and add two jumper wires (red).



This photograph shows the completed Arduino PCB, with the BNC connector fitted.

Note the LPF module plugged in (three yellow toroids) and the QRP Labs Si5351A synthesiser module kit plugged in.

When plugging in modules, be sure to orientate them correctly! The "In" and "Out" labels on the LPF must correspond with the labels on the shield PCB.

Take care to orientate the Si5351A Synth board correctly too! The silkscreen printing on the Si5351A board should be "upside down" compared to the shield PCB!



### 3.9 Relay-switched LPF board

This Arduino shield kit is compatible with the QRP Labs relay-switched LPF kit. This expands the capability of your project to switch between LPFs for 6 different bands (one on the main PCB, and five on the relay PCB).

The relay RL1 and diode D1 are supplied with the relay-switched LPF kit. The relay-switched LPF kit also includes the 2 x 5-pin connectors between the boards. The 2 x 5-pin "tall header" should be soldered into the shield PCB. The installation of the 2 x 5-pin "tall header" connector, RL1 and D1 are shown in the following diagram.



The relay-switched LPF kit also includes four 25mm nylon hex spacers. These may be fitted at the corners, the red circles shown in the above diagram. The shield kit includes four M3 nuts for this purpose.

These three photographs show the three types of synthesiser module that can be used.

Below: QRP Labs Si5351A synthesiser module kit

Bottom left: AD9850 DDS module (e.g. from eBay)

Bottom right: QRP Labs OCXO/Si5351A synthesiser module kit





### 3.10 Prototyping area

The shield PCB also includes a prototyping area, which you can use to construct your own circuits. If you are using the OCXO/Si5351A module kit, then there will be a height restriction as the OCXO/Si5351A module kit will overhang the prototyping area. Similarly if you chose to solder the synthesiser module directly into the PCB, rather than using the 10-way header connectors, then you will not have space to use the prototyping area.

Note that the bottom row of the prototyping area contains pads which are connected to the groundplane. The prototyping area is shown in the red rectangle in the diagram below, and the row of grounded pins within the black rectangle.



## 3.11 GPS connection options

At the right edge of the shield PCB are four pads which may be used to connect a GPS receiver module such as the QRP Labs QLG1 kit. Your Arduino sketch can use this for decoding position and time (etc.) information from the NMEA serial data stream from the GPS; and/or use the 1pps signal for calibrating the frequency and accurate timekeeping. This is similar to the use of the GPS receiver module with the QRP Labs Ultimate3 QRSS/WSPR kit. The connections of the GPS pads are shown in the diagram to the right.



Note that you will need to add a jumper wire, to supply 3.3V or 5V power to the GPS module. In the example in the diagram, the GPS is being supplied 5V, by connecting a jumper between the "GPS V" pad and the adjacent "5V" pad. Check your GPS requirements carefully. If your GPS requires 3.3V, you can connect the jumper wire instead between "GPS V" and "3.3V", to use the Arduino's 3.3V supply.

#### 3.12 Arduino pin assignments

The following table shows the pin assignments to use in the Arduino sketch, to access the various functions of this shield.

Band 0	7	Set low (0) to activate relay 0 (on main shield PCB) when fitted [1]
Band 1	A0	Set low (0) to activate relay 1 (on relay PCB) when fitted [1]
Band 2	10	Set low (0) to activate relay 2 (on relay PCB) when fitted [1]
Band 3	11	Set low (0) to activate relay 3 (on relay PCB) when fitted [1]
Band 4	12	Set low (0) to activate relay 4 (on relay PCB) when fitted [1]
Band 5	A3	Set low (0) to activate relay 5 (on relay PCB) when fitted [1]
GPS 1pps	9	1pps input from GPS: use a pin change interrupt in the sketch [2]
GPS RxD	0	Serial data from GPS: connected to processor serial interface [3]
Clk0	5	Si5351A Clk0 output is connected to Arduino pin 5 [4]
Clk2	1	Si5351A Clk2 output is connected to Arduino pin 1
SDA/DATA	A4 (SDA)	I2C interface for Si5351A; or Data signal if using AD9850 DDS [5]
SCL/FQUD	A5 (SCL)	I2C interface for Si5351A; or FQUD signal if using AD9850 DDS [5]
WCLK	3	WCLK signal if using AD9850 DDS [6]

## QRP Labs shield Arduino pin Comment

#### Notes:

- 1) Band switch relays output pins are set to low (0) to activate the relay; they can be set to 1 or highimpedance (define as input) to de-activate the relay
- 2) The best way to detect the 1pps signal from the GPS is to use a pin-change interrupt.
- 3) The suggested RxD (serial data) signal from the GPS is wired to Arduino pin 0, which also happens to be the standard UART peripheral serial data input pin on the microcontroller; this means that the standard serial data libraries can be used for handling the data from the GPS. Standard 9600 baud settings are used on most GPS modules.
- 4) The Si5351A Clk0 and Clk2 outputs are connected to Arduino pins 5 and 1 respectively. These pins on the Arduino should NOT be defined as outputs! They should always be inputs! They can be used for frequency counting purposes. This applies particularly to the pin 5 input which is the AVR's Timer1 counter. Using it may require some tricks in the Arduino sketch, to disable the Arduino's behind-the-scenes user of Timer1. So it is a more advanced topic.
- 5) The I2C interface on the Si5351A module has the two wires (SCL, SDA) connected to the standard TWI (two wire interface) pins on the microcontroller, this means the standard I2C communications libraries can be used. When using a AD9850 DDS module, it will be necessary to bit-bang these pins to act as DATA and FQUD signals respectively.
- 6) The WCLK signal applies only to the AD9850 DDS and should be bit-banged as WCLK when using the AD9850 DDS. Care should be taken when using the Si5351A module kit. This connection is pin 11 of the Si5351A module kit. On the Si5351A module, pin 11 may be connected to ground, depending on what PCB revision you have. If this is the case, you should make sure not to define this pin (Arduino pin 3) as output. Please see your Si5351A assembly instructions document.

## 4. Resources

Please see the kit page <u>http://qrp-labs.com/uarduino</u> for any information on latest updates and issues, and for sample sketches to use with the Arduino shield.

## 5. Version History

- 0 30-Apr-2015
  - First version
- 1 19-Mar-2019
  - Updated for changed trimmer pot, value is now 4.7K

## 2 02-Jan-2020

- Updated link in Resources section, to the correct kit web page
- Correct C10 and C11 which were swapped in the parts list